ENGR 3321: Introduction to Deep Learning for Robotics

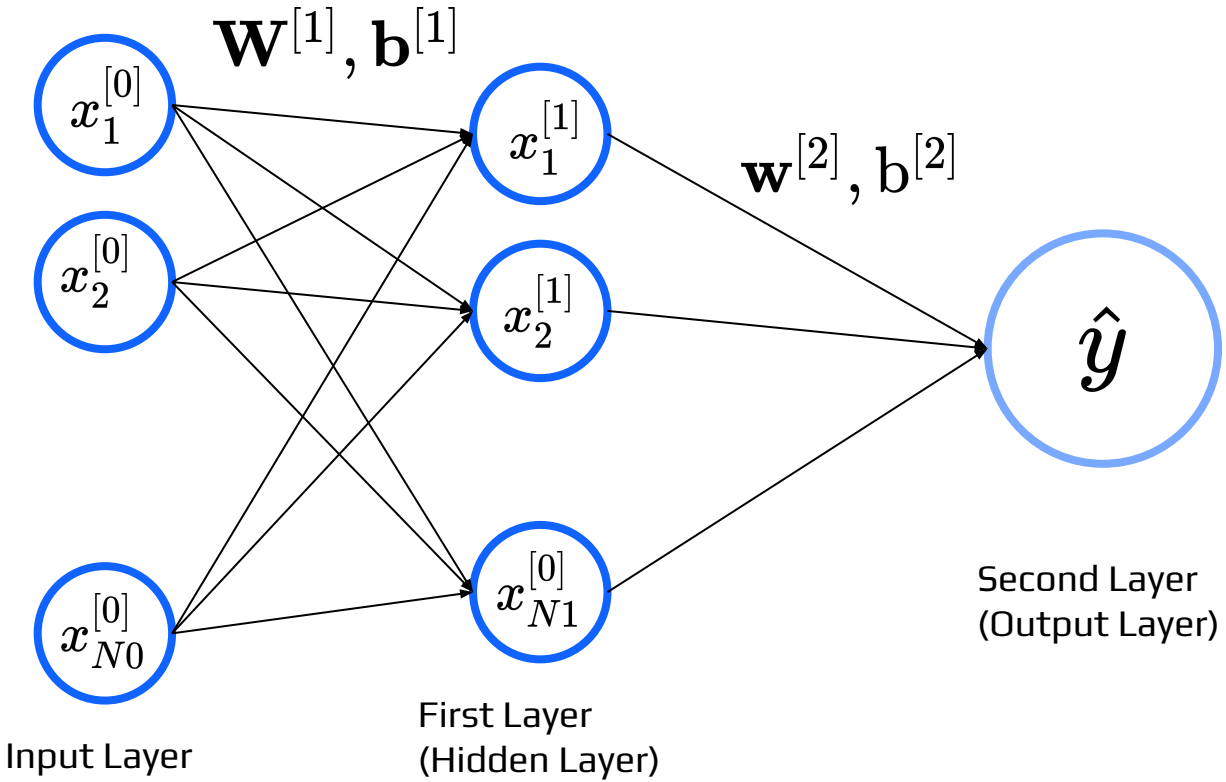
Neural Network N11: 1-Hidden Layer Model

10/30/2023

Outline

- Representations
- Layers
- Back-Propagation
- Gradient Descent

1 Hidden Layer Neural Network



Individual Representation

$$\hat{y} = \sigma\left(w_1^{[2]}x_1^{[1]} + w_2^{[2]}x_2^{[1]} + \ldots + w_{N_1}^{[2]}x_{N_1}^{[1]} + b^{[2]}\right)$$

Where

$$x_1^{[1]} = \sigma\left(w_{11}^{[1]}x_1^{[0]} + w_{21}^{[1]}x_2^{[0]} + \ldots + w_{N_0 1}^{[1]}x_{N_0}^{[0]} + b_1^{[1]}\right)$$

$$x_2^{[1]} = \sigma\left(w_{12}^{[1]}x_1^{[0]} + w_{22}^{[1]}x_2^{[0]} + \ldots + w_{N_0 2}^{[1]}x_{N_0}^{[0]} + b_2^{[1]}\right)$$

$$\vdots$$

$$x_{N_1}^{[1]} = \sigma\left(w_{1N_1}^{[1]}x_1^{[0]} + w_{2N_1}^{[1]}x_2^{[0]} + \ldots + w_{N_0 N_1}^{[1]}x_{N_0}^{[0]} + b_{N_1}^{[1]}\right)$$

Matrix Form

$$\begin{aligned}\hat{\mathbf{y}} &= \sigma\left(\mathbf{X}^{[1]} \cdot \mathbf{w}^{[2]\mathrm{T}} + b^{[2]}\right) \\ &= \sigma\left(\sigma\left(\mathbf{X}^{[0]} \cdot \mathbf{W}^{[1]\mathrm{T}} + \mathbf{b}^{[1]}\right) \cdot \mathbf{w}^{[2]\mathrm{T}} + b^{[2]}\right)\end{aligned}$$

Feature (Input) Matrix

$$\mathbf{X}^{[0]} = \begin{bmatrix} {}^{(1)}x_1^{[0]} & {}^{(1)}x_2^{[0]} & \dots & {}^{(1)}x_{N_0}^{[0]} \\ {}^{(2)}x_1^{[0]} & {}^{(2)}x_2^{[0]} & \dots & {}^{(2)}x_{N_0}^{[0]} \\ & & \dots & \\ {}^{(M)}x_1^{[0]} & {}^{(1)}x_2^{[0]} & \dots & {}^{(M)}x_{N_0}^{[0]} \end{bmatrix}_{(M,N_0)}$$

First-Layer Parameters

$$\mathbf{W}^{[1]} = \begin{bmatrix} w_{11}^{[1]} & w_{21}^{[1]} & \dots & w_{N_0 1}^{[1]} \\ w_{12}^{[1]} & w_{22}^{[1]} & \dots & w_{N_0 2}^{[1]} \\ & & \dots & \\ w_{1N_1}^{[1]} & w_{2N_1}^{[1]} & \dots & w_{N_0 N_1}^{[1]} \end{bmatrix}_{(N_1, N_0)}$$

$$\mathbf{b}^{[1]} = \begin{bmatrix} b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \end{bmatrix}_{(1, N_1)}$$

Second-Layer Parameters

$$\mathbf{w}^{[2]} = \begin{bmatrix} w_1^{[2]} & w_2^{[2]} & \dots & w_{N_1}^{[2]} \end{bmatrix}_{(1,N_1)}$$

$b^{[2]}$, scalar

Forward Propagation

$$\mathbf{X}^{[1]} = \sigma\left(\mathbf{X} \cdot \mathbf{W}^{[1]\mathrm{T}} + \mathbf{b}^{[1]}\right) = \sigma\left(\mathbf{Z}^{[1]}\right)$$

$$\mathbf{X}^{[1]} = \sigma\left(\begin{bmatrix} {}^{(1)}x_1^{[0]} & {}^{(1)}x_2^{[0]} & \dots & {}^{(1)}x_{N_0}^{[0]} \\ {}^{(2)}x_1^{[0]} & {}^{(2)}x_2^{[0]} & \dots & {}^{(2)}x_{N_0}^{[0]} \\ & & \dots & \\ {}^{(M)}x_1^{[0]} & {}^{(M)}x_2^{[0]} & \dots & {}^{(M)}x_{N_0}^{[0]} \end{bmatrix} \cdot \begin{bmatrix} w_{11}^{[1]} & w_{12}^{[1]} & \dots & w_{1N_1}^{[1]} \\ w_{21}^{[1]} & w_{22}^{[1]} & \dots & w_{2N_1}^{[1]} \\ & & \dots & \\ w_{N_0 1}^{[1]} & w_{N_0 2}^{[1]} & \dots & w_{N_0 N_1}^{[1]} \end{bmatrix} + \begin{bmatrix} b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \\ b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \\ & & \dots & \\ b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \end{bmatrix}\right)$$

$$\hat{\mathbf{y}} = \sigma\left(\mathbf{X}^{[1]}\mathbf{w}^{[\mathbf{2}]\mathrm{T}} + b^{[2]}\right) = \sigma\left(\mathbf{Z}^{[2]}\right)$$

$$\hat{\mathbf{y}} = \sigma\left(\begin{bmatrix} {}^{(1)}x_1^{[0]} & {}^{(1)}x_2^{[1]} & \dots & {}^{(1)}x_{N_1}^{[1]} \\ {}^{(2)}x_1^{[1]} & {}^{(2)}x_2^{[1]} & \dots & {}^{(2)}x_{N_1}^{[1]} \\ & & \dots & \\ {}^{(M)}x_1^{[1]} & {}^{(M)}x_2^{[1]} & \dots & {}^{(M)}x_{N_1}^{[1]} \end{bmatrix} \cdot \begin{bmatrix} w_1^{[2]} \\ w_2^{[2]} \\ \dots \\ w_{N_1}^{[2]} \end{bmatrix} + \begin{bmatrix} b^{[2]} \\ b^{[2]} \\ \dots \\ b^{[2]} \end{bmatrix}\right)$$

Target and Prediction

$$\mathbf{y} = \begin{bmatrix} {}^{(1)}y \\ {}^{(2)}y \\ . \\ . \\ . \\ {}^{(M)}y \end{bmatrix}_{(M,1)}$$

$$\hat{\mathbf{y}} = \begin{bmatrix} {}^{(1)}\hat{y} \\ {}^{(2)}\hat{y} \\ . \\ . \\ . \\ {}^{(M)}\hat{y} \end{bmatrix}_{(M,1)}$$

Binary Cross Entropy Loss

$$\mathcal{L}(\hat{\mathbf{y}}, \mathbf{y}) = \frac{1}{M}\Sigma(-\mathbf{y}\log_e(\hat{\mathbf{y}}) - (1-\mathbf{y})\log_e(1-\hat{\mathbf{y}}))$$

Back-Propagation

$$\nabla \mathcal{L} = \left[\frac{\partial \mathcal{L}}{\partial w_{11}^{[1]}} \quad \cdots \quad \frac{\partial \mathcal{L}}{\partial w_{\mathrm{N}_1\mathrm{N}_0}^{[1]}} \quad \frac{\partial \mathcal{L}}{\partial b_1^{[1]}} \quad \cdots \quad \frac{\partial \mathcal{L}}{\partial b_{\mathrm{N}_1}^{[1]}} \quad \frac{\partial \mathcal{L}}{\partial w_1^{[2]}} \quad \cdots \quad \frac{\partial \mathcal{L}}{\partial w_{\mathrm{N}_1}^{[2]}} \quad \frac{\partial \mathcal{L}}{\partial b^{[2]}} \right]$$

$$= \left[\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{[1]}} \quad \frac{\partial \mathcal{L}}{\partial \mathbf{b}^{[1]}} \quad \frac{\partial \mathcal{L}}{\partial \mathbf{w}^{[2]}} \quad \frac{\partial \mathcal{L}}{\partial \mathrm{b}^{[2]}} \right]$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}^{[2]}} = \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \cdot \frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{Z}^{[2]}} \cdot \frac{\partial \mathbf{Z}^{[2]}}{\partial \mathbf{w}^{[2]}} = \frac{1}{M} (\hat{\mathbf{y}} - \mathbf{y})^T \cdot \mathbf{X}^{[1]}$$

$$\frac{\partial \mathcal{L}}{\partial b^{[2]}} = \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \cdot \frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{Z}^{[2]}} \cdot \frac{\partial \mathbf{Z}^{[2]}}{\partial b^{[2]}} = \frac{1}{M} \sum (\hat{\mathbf{y}} - \mathbf{y})$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{X}^{[1]}} = \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \cdot \frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{Z}^{[2]}} \cdot \frac{\partial \mathbf{Z}^{[2]}}{\partial \mathbf{X}^{[1]}} = (\hat{\mathbf{y}} - \mathbf{y}) \cdot \mathbf{w}^{[2]}$$

Back-Propagation

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{[1]}} = \frac{\partial \mathcal{L}}{\partial \mathbf{X}^{[1]}} \cdot \frac{\partial \mathbf{X}^{[1]}}{\partial \mathbf{Z}^{[1]}} \cdot \frac{\partial \mathbf{Z}^{[1]}}{\partial \mathbf{W}^{[1]}} = \frac{1}{M} \left[(\hat{\mathbf{y}} - \mathbf{y}) \cdot \mathbf{w}^{[2]} * \mathbf{X}^{[1]} * \left(1 - \mathbf{X}^{[1]} \right) \right]^T \cdot \mathbf{X}^{[0]}$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{b}^{[1]}} = \frac{\partial \mathcal{L}}{\partial \mathbf{X}^{[1]}} \cdot \frac{\partial \mathbf{X}^{[1]}}{\partial \mathbf{Z}^{[1]}} \cdot \frac{\partial \mathbf{Z}^{[1]}}{\partial \mathbf{b}^{[1]}} = \frac{1}{M} \Sigma \left[(\hat{\mathbf{y}} - \mathbf{y}) \cdot \mathbf{w}^{[2]} * \mathbf{X}^{[1]} * \left(1 - \mathbf{X}^{[1]} \right) \right]^T, \text{ axis=0}$$

Gradient Descent Optimization

Given dataset: $\left\{ \left({}^{(1)}\mathbf{x}, {}^{(1)}y \right), \left({}^{(2)}\mathbf{x}, {}^{(2)}y \right), \ldots, \left({}^{(M)}\mathbf{x}, {}^{(M)}y \right) \right\}$

Initialize $\mathbf{W}^{[1]}$, $\mathbf{w}^{[2]}$, $\mathbf{b}^{[1]}$ and $b^{[2]}$

Repeat until converge {

$$\mathbf{W}^{[1]} := \mathbf{W}^{[1]} - \alpha \frac{\partial \mathcal{L}}{\partial \mathbf{W}^{[1]}}$$

$$\mathbf{w}^{[2]} := \mathbf{w}^{[2]} - \alpha \frac{\partial \mathcal{L}}{\partial \mathbf{w}^{[2]}}$$

$$\mathbf{b}^{[1]} := \mathbf{b}^{[1]} - \alpha \frac{\partial \mathcal{L}}{\partial \mathbf{b}^{[1]}}$$

$$b^{[2]} := b^{[2]} - \alpha \frac{\partial \mathcal{L}}{\partial b^{[2]}}$$

}

where α is learning rate