ENGR 3321:Introduction to Deep Learning for Robotics

Neural Network 101: SISO Linear Function



Outline

- Simplest neural network model: NN101
- Model learning/training

Neural Network





Neural Network == Function



SISO Neural Network (NN101)



NN101 == Linear Model

$$\hat{y} = f(x) = wx + b$$

Linear Model Examples

 $\hat{y} = 15x$

 $\hat{y} = -3x + 25$

Temperature conversion

Hourly wage

Car decelerate

Automatic Pattern Learning

- 1. Guess a model.
- 2. Evaluate the model .
- 3. Find out hints to improve the model.
- 4. Perform improvements.
- 5. Repeat 2 to 4 until converge.

Example: Predict Used Car Price

Mileage (10,000 miles)	Selling Price (\$10,000)
5.7923	3.359
7.1229	2.259
1.9160	3.959
4.1124	3.099
12.8000	1.5
6.8696	2.799
2.9499	3.459
4.3000	3.5
1.7302	2.999
3.0237	3.859

Dataset: $\mathcal{D} = \{({}^{(1)}x,{}^{(1)}y),({}^{(2)}x,{}^{(2)}y),\ldots,({}^{(M)}x,{}^{(M)}y)\}$

Initial Guess

Evaluate Model Performance

Mean Squared Error (MSE) function

$$\mathcal{L}(\hat{\mathbf{y}}, \mathbf{y}) = \frac{1}{M} \sum_{i=1}^{M} \frac{1}{2} ({}^{(i)}\hat{y} - {}^{(i)}y)^2$$

Gradient/Derivatives

$$\nabla \mathcal{L}(w,b) = \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial w} \\ \frac{\partial \mathcal{L}}{\partial b} \end{bmatrix} = \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \frac{\partial \hat{\mathbf{y}}}{\partial w} \\ \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \frac{\partial \hat{\mathbf{y}}}{\partial b} \end{bmatrix} = \begin{bmatrix} \frac{1}{M} \sum_{i=1}^{M} \binom{(i)}{i} \hat{y} - \binom{(i)}{i} y \binom{(i)}{i} x \\ \frac{1}{M} \sum_{i=1}^{M} \binom{(i)}{i} \hat{y} - \binom{(i)}{i} y \end{bmatrix}$$
Chain Rule

Gradient Descent Concept

Find w and b that minimize $\mathcal{L}(w, b)$

Gradient Descent Algorithm

Initialize w and b

Repeat until converge {

$$w:=w-lpharac{\partial \mathcal{L}}{\partial w} \ b:=b-lpharac{\partial \mathcal{L}}{\partial w}$$

where α is learning rate

Loss Decrease

Trained Model

Derivative Review

the derivative of a function at a given point gives us the rate of change or slope of the tangent line to the function at that point.