# ENGR 3321: Introduction to Deep Learning for Robotics

Neural Network N11:

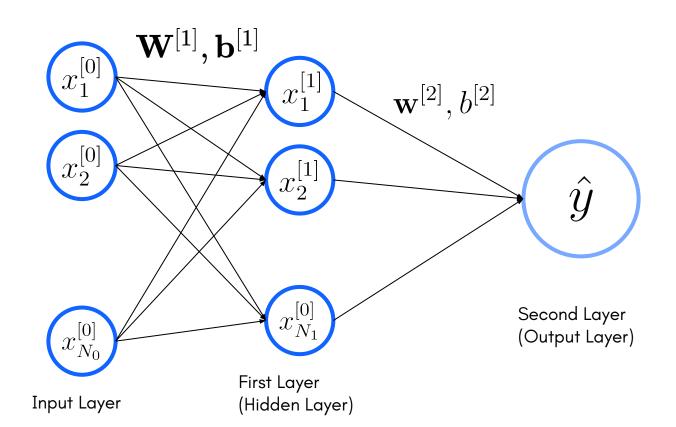
Multi-Input, One-Hidden Layer, One-Output Model



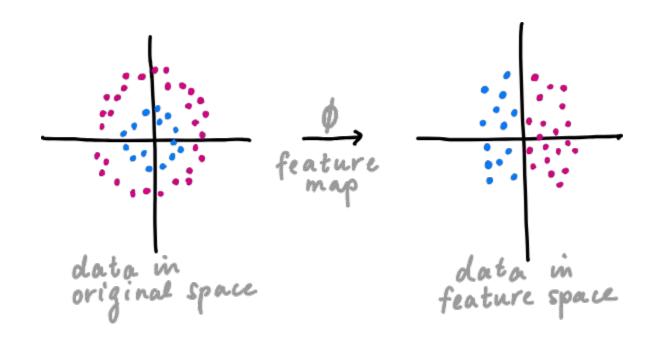
#### Outline

- Representations
- Back-Propagation
- Gradient Descent

#### 1 Hidden Layer Neural Network



#### Feature Transformation



# Individual Representation

$$\hat{y} = \sigma \Big( w_1^{[2]} x_1^{[1]} + w_2^{[2]} x_2^{[1]} {+} \ldots {+} w_{N_1}^{[2]} x_{N_1}^{[1]} + b^{[2]} \Big)$$

Where

## Input Feature Matrix

 $\mathbf{X}^{[1]} 
eq [$ 

### First-Layer Parameters

$$\mathbf{b}^{[1]} = egin{bmatrix} b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \end{bmatrix}_{(1,N_1)}$$

## Second-Layer Parameters

$$\mathbf{w}^{[2]} = egin{bmatrix} w_1^{[2]} & w_2^{[2]} & \dots & w_{N_1}^{[2]} \end{bmatrix}_{(1,N_1)}$$

 $b^{[2]}$ , scalar

# Forward Propagation

$$\mathbf{X}^{[1]} = \sigma \Big( \mathbf{X} \cdot \mathbf{W}^{[1]\mathrm{T}} {+} \mathbf{b}^{[1]} \Big) = \sigma \Big( \mathbf{Z}^{[1]} \Big)$$

$$\mathbf{X}^{[1]} = \sigma \begin{pmatrix} \begin{bmatrix} ^{(1)}x_1^{[0]} & ^{(1)}x_2^{[0]} & \dots & ^{(1)}x_{N_0}^{[0]} \\ ^{(2)}x_1^{[0]} & ^{(2)}x_2^{[0]} & \dots & ^{(2)}x_{N_0}^{[0]} \\ & & & & & \\ ^{(M)}x_1^{[0]} & ^{(M)}x_2^{[0]} & \dots & ^{(M)}x_{N_0}^{[0]} \end{bmatrix} \cdot \begin{bmatrix} w_{11}^{[1]} & w_{12}^{[1]} & \dots & w_{1N_1}^{[1]} \\ w_{21}^{[1]} & w_{22}^{[1]} & \dots & w_{2N_1}^{[1]} \\ & & & & & \\ w_{N_01}^{[1]} & w_{N_02}^{[1]} & \dots & w_{N_0N_1}^{[1]} \end{bmatrix} + \begin{bmatrix} b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \\ b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \\ & & & & & \\ b_1^{[1]} & b_2^{[1]} & \dots & b_{N_1}^{[1]} \end{bmatrix} \end{pmatrix}$$

$$\hat{\mathbf{y}} = \sigma \Big( \mathbf{X}^{[1]} \mathbf{w}^{[\mathbf{2}]\mathrm{T}} \!+\! b^{[2]} \Big) = \sigma \Big( \mathbf{Z}^{[2]} \Big)$$

$$\mathbf{\hat{y}} = \sigma \left( egin{bmatrix} ^{(1)}x_1^{[0]} & ^{(1)}x_2^{[1]} & \dots & ^{(1)}x_{N_1}^{[1]} \ ^{(2)}x_1^{[1]} & ^{(2)}x_2^{[1]} & \dots & ^{(2)}x_{N_1}^{[1]} \ & & & \dots & \ ^{(M)}x_1^{[1]} & ^{(M)}x_2^{[1]} & \dots & ^{(M)}x_{N_1}^{[1]} \ \end{pmatrix} \cdot egin{bmatrix} w_1^{[2]} \ w_2^{[2]} \ \dots \ w_2^{[2]} \ \end{pmatrix} + egin{bmatrix} b^{[2]} \ b^{[2]} \ \dots \ b^{[2]} \ \end{pmatrix} 
ight)$$

## Target and Prediction

$$\mathbf{y} = egin{bmatrix} ^{(1)}y \ ^{(2)}y \ ^{\cdot} \ ^{\cdot} \ ^{\cdot} \ ^{(M)}y \end{bmatrix}_{(M,1)}$$

$$\mathbf{\hat{y}} = egin{bmatrix} ^{(1)} \hat{y} \ ^{(2)} \hat{y} \ ^{\cdot} \ ^{\cdot} \ ^{\cdot} \ ^{(M)} \hat{y} \end{bmatrix}_{(M,1)}$$

#### Matrix Form

$$egin{aligned} \hat{\mathbf{y}} &= \sigma(\mathbf{X}^{[1]} \cdot \mathbf{w}^{[2]T} + b^{[2]}) \ &= \sigma(\sigma(\mathbf{X}^{[0]} \cdot \mathbf{W}^{[1]T} + \mathbf{b}^{[1]}) \cdot \mathbf{w}^{[2]T} + b^{[2]}) \ &= \sigma(\sigma(\mathbf{X}^{[0]} \cdot \mathbf{W}^{[0]} \cdot \mathbf{W}^{[1]T} + \mathbf{b}^{[1]}) \cdot \mathbf{w}^{[2]T} + b^{[2]}) \end{aligned}$$

#### Binary Cross Entropy Loss

$$\mathcal{L}(\hat{\mathbf{y}}, \mathbf{y}) = \frac{1}{M} \sum_{i=1}^{M} -^{(i)} y \ln^{(i)} \hat{y} - (1 - ^{(i)} y) \ln(1 - ^{(i)} \hat{y}) = \overline{-\mathbf{y} \ln \hat{\mathbf{y}} - (1 - \mathbf{y}) \ln(1 - \hat{\mathbf{y}})}$$

# Back-Propagation (2nd layer)

$$\nabla \mathcal{L} = \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial w_{11}^{[1]}} & \cdots & \frac{\partial \mathcal{L}}{\partial w_{N_1 N_0}^{[1]}} & \frac{\partial \mathcal{L}}{\partial b_1^{[1]}} & \cdots & \frac{\partial \mathcal{L}}{\partial b_{N_1}^{[1]}} & \frac{\partial \mathcal{L}}{\partial w_1^{[2]}} & \cdots & \frac{\partial \mathcal{L}}{\partial w_{N_1}^{[2]}} & \frac{\partial \mathcal{L}}{\partial b^{[2]}} \end{bmatrix} \\
= \begin{bmatrix} \frac{\partial \mathcal{L}}{\partial \mathbf{W}^{[1]}} & \frac{\partial \mathcal{L}}{\partial \mathbf{b}^{[1]}} & \frac{\partial \mathcal{L}}{\partial \mathbf{w}^{[2]}} & \frac{\partial \mathcal{L}}{\partial b^{[2]}} \end{bmatrix}$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{w}^{[2]}} = \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} \frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{Z}^{[2]}} \frac{\partial \mathbf{Z}^{[2]}}{\partial \mathbf{w}^{[2]}} = \frac{1}{M} (\hat{\mathbf{y}} - \mathbf{y})^T \cdot \mathbf{X}^{[1]}$$

$$rac{\partial \mathcal{L}}{\partial b^{[2]}} = rac{\partial \mathcal{L}}{\partial \hat{\mathbf{y}}} rac{\partial \hat{\mathbf{y}}}{\partial \mathbf{Z}^{[2]}} rac{\partial \mathbf{Z}^{[2]}}{\partial b^{[2]}} = \overline{\hat{\mathbf{y}} - \mathbf{y}}$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{X}^{[1]}} = \frac{\partial \mathcal{L}}{\partial \hat{\mathbf{v}}} \frac{\partial \hat{\mathbf{y}}}{\partial \mathbf{Z}^{[2]}} \frac{\partial \mathbf{Z}^{[2]}}{\partial \mathbf{X}^{[1]}} = (\hat{\mathbf{y}} - \mathbf{y}) \cdot \mathbf{w}^{[2]}$$

# Back-Propagation (1st layer)

$$\frac{\partial \mathcal{L}}{\partial \mathbf{W}^{[1]}} = \frac{\partial \mathcal{L}}{\partial \mathbf{X}^{[1]}} \frac{\partial \mathbf{X}^{[1]}}{\partial \mathbf{Z}^{[1]}} \frac{\partial \mathbf{Z}^{[1]}}{\partial \mathbf{W}^{[1]}} = \frac{1}{M} [(\hat{\mathbf{y}} - \mathbf{y}) \cdot \mathbf{w}^{[2]} * \mathbf{X}^{[1]} * (1 - \mathbf{X}^{[1]})]^T \cdot \mathbf{X}^{[0]}$$

$$\frac{\partial \mathcal{L}}{\partial \mathbf{b}^{[1]}} = \frac{\partial \mathcal{L}}{\partial \mathbf{X}^{[1]}} \frac{\partial \mathbf{X}^{[1]}}{\partial \mathbf{z}^{[1]}} \frac{\partial \mathbf{Z}^{[1]}}{\partial \mathbf{b}^{[1]}} = \overline{(\hat{\mathbf{y}} - \mathbf{y}) \cdot \mathbf{w}^{[2]} * \mathbf{X}^{[1]} * (1 - \mathbf{X}^{[1]})}, \text{ axis} = 0$$

# Gradient Descent Optimization

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Given dataset: \left\{ \left( {^{(1)}}\mathbf{x}, {^{(1)}}y \right), \left( {^{(2)}}\mathbf{x}, {^{(2)}}y \right), \dots, \left( {^{(M)}}\mathbf{x}, {^{(M)}}y \right) \right\}
Initialize \mathbf{W}^{[1]}, \mathbf{w}^{[2]}, \mathbf{b}^{[1]} and b^{[2]}
Repeat until converge {
           \mathbf{W}^{[1]} := \mathbf{W}^{[1]} - lpha rac{\partial \mathcal{L}}{\partial \mathbf{W}^{[1]}}
          \mathbf{w}^{[2]} := \mathbf{w}^{[2]} - lpha rac{\partial \mathcal{L}}{\partial \mathbf{w}^{[2]}}
          \mathbf{b}^{[1]} := \mathbf{b}^{[1]} - lpha rac{\partial \mathcal{L}}{\partial \mathbf{b}^{[1]}}
          b^{[2]}:=b^{[2]}-lpharac{\partial \mathcal{L}}{\partial b^{[2]}}
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where  $\alpha$  is learning rate