ENGR 3321: Introduction to Deep Learning for Robotics

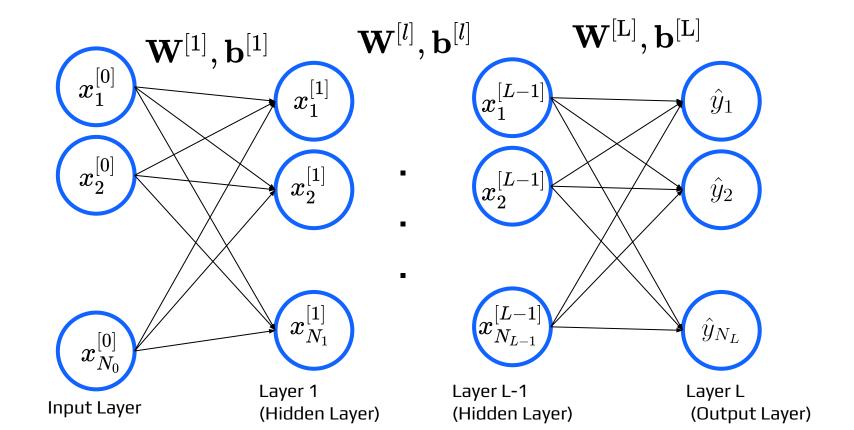
Neural Network NNN: Multi-Layer Perceptron Model



Outline

- Representations
- Multi-Class Classification

Multi-Layer Perceptron Model



Individual Representation

$$x_n^{[l]} = a(w_{1n}^{[l]}x_1^{[l-1]} + w_{2n}^{[l]}x_2^{[l-1]} + \dots + w_{N_{l-1}n}^{[l]}x_{N_{l-1}}^{[l-1]} + b_n^{[l]})$$

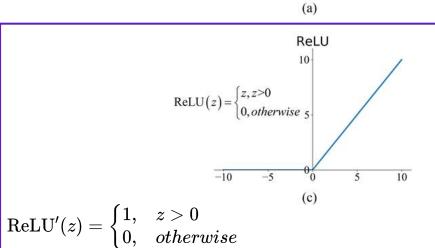
Matrix Form

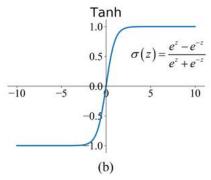
$$\mathbf{X}^{[l]} = a(\mathbf{Z}^{[l]}) = a(\mathbf{X}^{[l-1]} \cdot \mathbf{W}^{[l]T} + \mathbf{b}^{[l]})$$

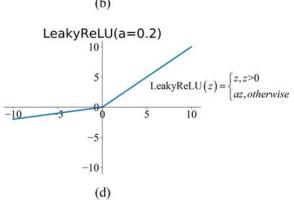
 $a(\cdot)$ activation function

Activation Functions

$$\sigma'(z)=\sigma(z)(1-\sigma(z))$$
 Sigmoid
$$\sigma(z)=\frac{1}{1+e^{-z}}$$







 $ext{LeakyReLU}'(z) = egin{cases} 1, & z > 0 \ a, & otherwise \end{cases}$

 $\sigma'(z) = 1 - \sigma^2(z)$

Feature (Input) Matrix

$$\mathbf{X}^{[0]} = egin{bmatrix} ^{(1)}x_1^{[0]} & ^{(1)}x_2^{[0]} & \dots & ^{(1)}x_{N_0}^{[0]} \ ^{(2)}x_1^{[0]} & ^{(2)}x_2^{[0]} & \dots & ^{(2)}x_{N_0}^{[0]} \ & & & \dots & & \ ^{(M)}x_1^{[0]} & ^{(1)}x_2^{[0]} & \dots & ^{(M)}x_{N_0}^{[0]} \end{bmatrix}_{(M,N_0)}$$

Trainable Parameters

$$\mathbf{W}^{[l]} = egin{bmatrix} w_{11}^{[l]} & w_{21}^{[l]} & \dots & w_{N_{l-1}1}^{[l]} \ w_{12}^{[l]} & w_{22}^{[l]} & \dots & w_{N_{l-1}2}^{[l]} \ & & \dots & & \ w_{1N_{l}}^{[l]} & w_{2N_{l}}^{[l]} & \dots & w_{N_{l-1}N_{l}}^{[l]} \ \end{pmatrix}_{(N_{l},N_{l-1})}$$

$$\mathbf{b}^{[l]} = egin{bmatrix} b_1^{[l]} & b_2^{[l]} & \dots & b_{N_l}^{[l]} \end{bmatrix}_{(1,N_l)}$$

Forward Propagation

$$\mathbf{Z}^{[l]} = \mathbf{X}^{[l-1]} \cdot \mathbf{W}^{[l]\mathrm{T}} {+} \mathbf{b}^{[l]}$$

$$\mathbf{X}^{[l]} = a\Big(\mathbf{Z}^{[l]}\Big)$$

Special Case:

$$\mathbf{\hat{Y}} = a \Big(\mathbf{X}^{[\mathrm{L}-1]} \mathbf{W}^{[\mathrm{L}]\mathrm{T}} \! + \! \mathbf{b}^{[\mathrm{L}]} \Big) = a \Big(\mathbf{Z}^{[\mathrm{L}]} \Big) = \mathbf{X}^{[\mathrm{L}]}$$

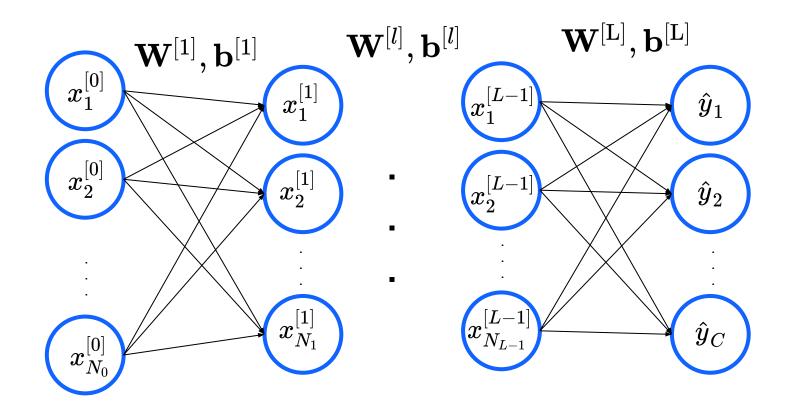
Prediction (output) Matrix

$$\hat{\mathbf{Y}} = \begin{bmatrix} {}^{(1)}y_1 & {}^{(1)}y_2 & \dots & {}^{(1)}y_{N_L} \\ {}^{(2)}y_1 & {}^{(2)}y_2 & \dots & {}^{(2)}y_{N_L} \\ & & & \ddots & \\ {}^{(M)}y_1 & {}^{(M)}y_2 & \dots & {}^{(M)}y_{N_L} \end{bmatrix}_{(M,N_L)}$$

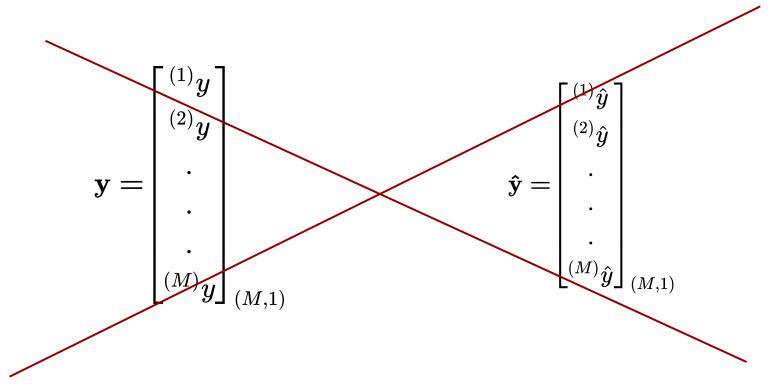
Gradient Descent Optimization

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Given dataset: \left\{ \left( {^{(1)}}\mathbf{x}, {^{(1)}}\mathbf{y} \right), \left( {^{(2)}}\mathbf{x}, {^{(2)}}\mathbf{y} \right), \dots, \left( {^{(M)}}\mathbf{x}, {^{(M)}}\mathbf{y} \right) \right\}
Initialize \mathbf{W}^{[l]}, \mathbf{b}^{[l]}
Repeat until converge {
         compute \mathcal{L}(\mathbf{\hat{Y}}, \mathbf{Y})
         compute \nabla \mathcal{L}
         \mathbf{W}^{[l]} := \mathbf{W}^{[l]} - \alpha \cdot d\mathbf{W}^{[l]}
         \mathbf{b}^{[l]} := \mathbf{b}^{[l]} - \alpha \cdot d\mathbf{b}^{[l]}
where \alpha is learning rate
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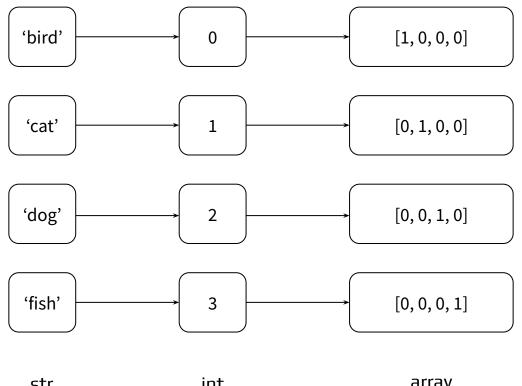
Multi-Class Classification



Multi-Class Classification



One-Hot Encoding on Targets



int str array

Softmax Activation on Predictions

$$\hat{y}_c = rac{e^{z_c^{[L]}}}{\sum_{c=1}^C e^{z_c^{[L]}}}, \, orall c = 1, \dots, C$$

$$\sum igl[^{(m)} \hat{y}_1 \quad ^{(m)} \hat{y}_2 \quad \dots \quad ^{(m)} \hat{y}_C igr] \, = 1$$

Probability of the *m*-th sample being predicted as a member in class 1

Multi-Class Classification

$$\mathbf{Y} = \begin{bmatrix} {}^{(1)}y_1 & {}^{(1)}2 & \dots & {}^{(1)}y_C \\ {}^{(2)}y_1 & {}^{(2)}y_2 & \dots & {}^{(2)}y_C \\ & & & & & & \\ {}^{(M)}y_1 & {}^{(M)}y_2 & & {}^{(M)}y_C \end{bmatrix}_{(M,C)} \qquad \hat{\mathbf{Y}} = \begin{bmatrix} {}^{(1)}\hat{y}_1 & {}^{(1)}\hat{y}_2 & \dots & {}^{(1)}\hat{y}_C \\ {}^{(2)}\hat{y}_1 & {}^{(2)}\hat{y}_2 & \dots & {}^{(2)}\hat{y}_C \\ & & & & & \\ {}^{(M)}\hat{y}_1 & {}^{(M)}\hat{y}_2 & & {}^{(M)}\hat{y}_C \end{bmatrix}_{(M,C)}$$

Multi-Class Cross Entropy Loss

$$\mathcal{L}ig(\mathbf{\hat{Y},Y}ig) = rac{1}{M} \sum_{m=1}^{M} \left[\sum_{c=1}^{C} \left(-^{(m)} y_c \ln^{(m)} \hat{y}_c
ight)
ight]$$

Back-Propagation

$$abla \mathcal{L} = egin{bmatrix} \cdots & rac{\partial \mathcal{L}}{\partial w_{l-1,l}^{[l]}} & \cdots & rac{\partial \mathcal{L}}{\partial b_{l}^{[l]}} & \cdots \end{bmatrix}$$

$$d\mathbf{Z}^{[L]} = \frac{\partial \mathcal{L}}{\partial \mathbf{\hat{Y}}} \cdot \frac{\partial \mathbf{\hat{Y}}}{\partial \mathbf{Z}^{[L]}} = \mathbf{\hat{Y}} - \mathbf{Y}$$
NOTE: Only valid if
1. last layer is softmax activated;
2. Prediction is evaluated by cross entropy loss

For l from L to 1

$$egin{aligned} d\mathbf{W}^{[l]} &= d\mathbf{Z}^{[l]} \cdot rac{\partial \mathbf{Z}^{[l]}}{\partial \mathbf{W}^{[l]}} = d\mathbf{Z}^{[l]T} \cdot \mathbf{X}^{[l-1]} \ d\mathbf{b}^{[l]} &= d\mathbf{Z}^{[l]} \cdot rac{\partial \mathbf{Z}^{[l]}}{\partial \mathbf{b}^{[l]}} = mean\Big(d\mathbf{Z}^{[l]}, \, ext{axis=0, keepdims=True}\Big) \ d\mathbf{X}^{[l-1]} &= d\mathbf{Z}^{[l]} \cdot rac{\partial \mathbf{Z}^{[l]}}{\partial \mathbf{X}^{[l-1]}} = d\mathbf{Z}^{[l]} \cdot \mathbf{W}^{[l]} \ d\mathbf{Z}^{[l-1]} &= d\mathbf{X}^{[l-1]} * a'\Big(\mathbf{Z}^{[l-1]}\Big) \end{aligned}$$