

ENGR 3321: Introduction to Deep Learning for Robotics

Convolutional Neural Network

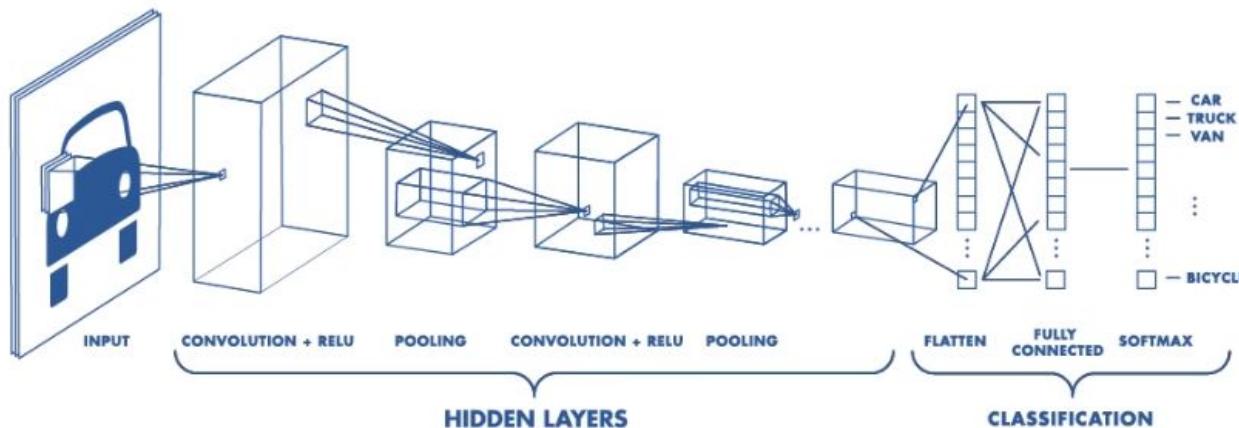
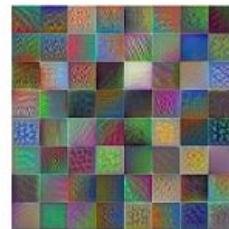
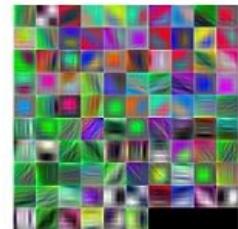
11/11/2024



Outline

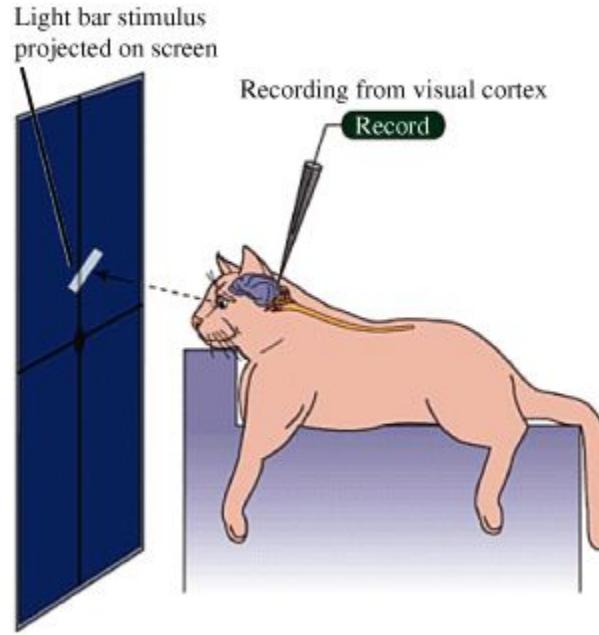
- Introduction
- Convolution Layer Principles
- Visualize Convolved Features
- Classical ConvNets

Convolutional Neural Network

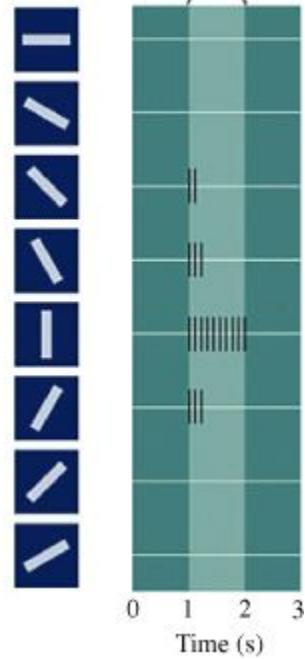


Hubel & Wiesel's Cat Experiment

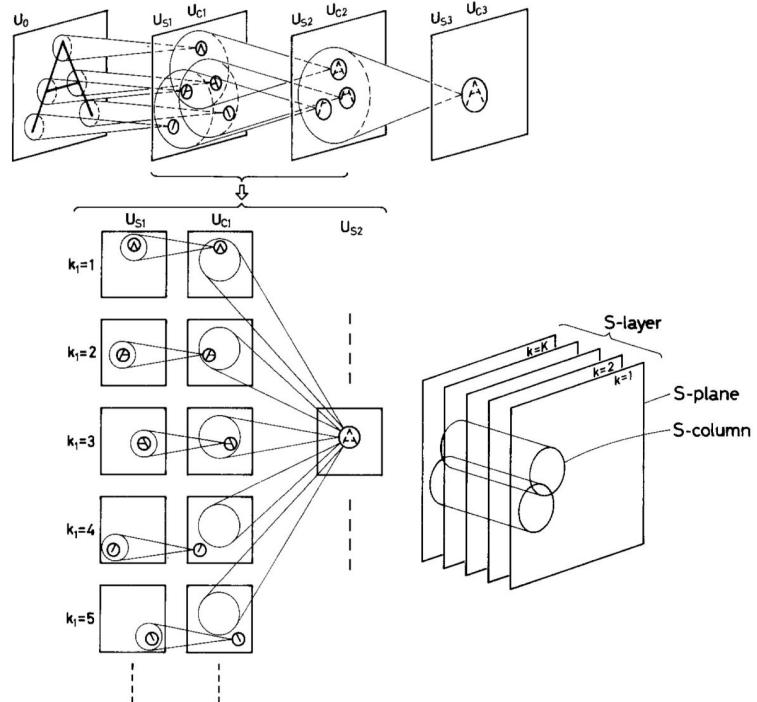
A Experimental setup



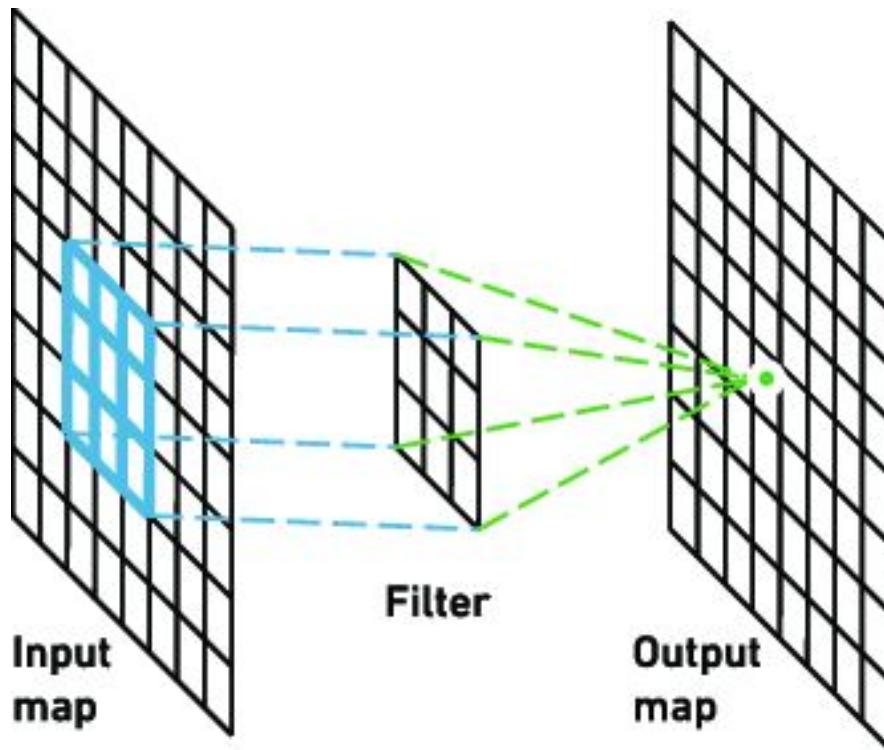
B Stimulus orientation Stimulus presented



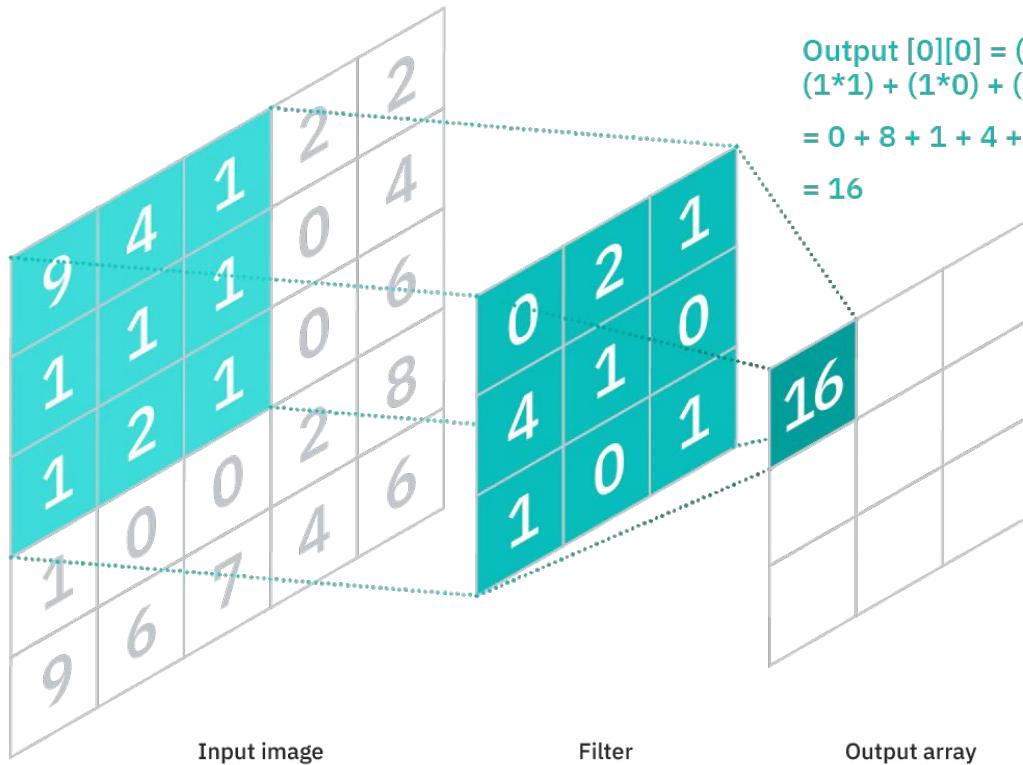
Early ConvNet



Convolution Layer



Convolution Operation



$$W_{out} = \frac{W_{in} - K + 2P}{S} + 1$$

Annotations for the formula:

- Kernel Size:** Points to the term K .
- Padding Size:** Points to the term P .
- Stride:** Points to the term S .

Pattern Detection

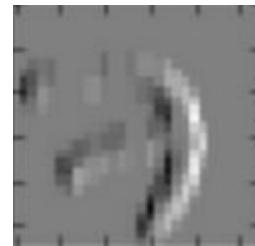
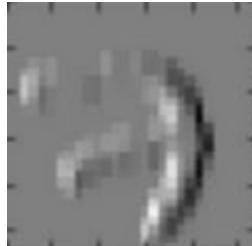


-1	-1	-1
1	1	1
0	0	0

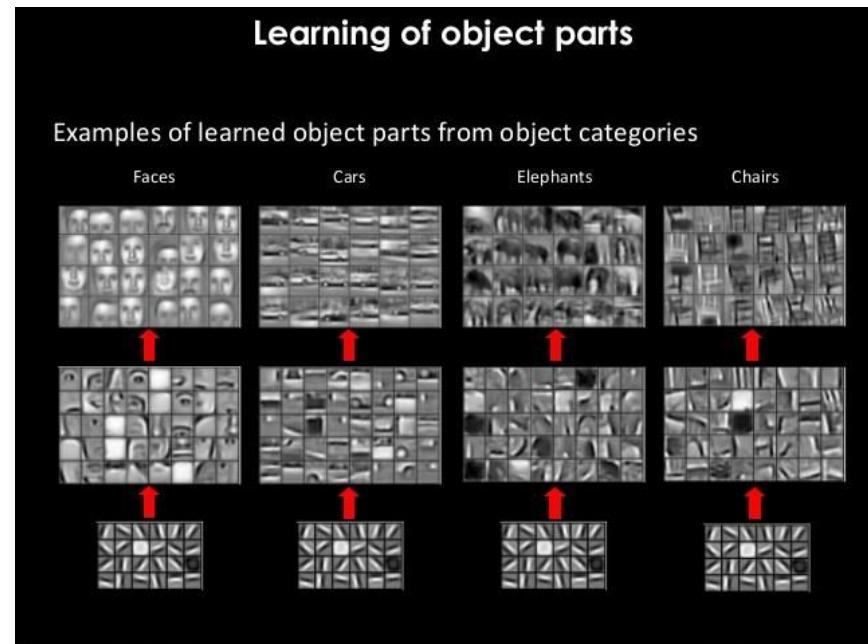
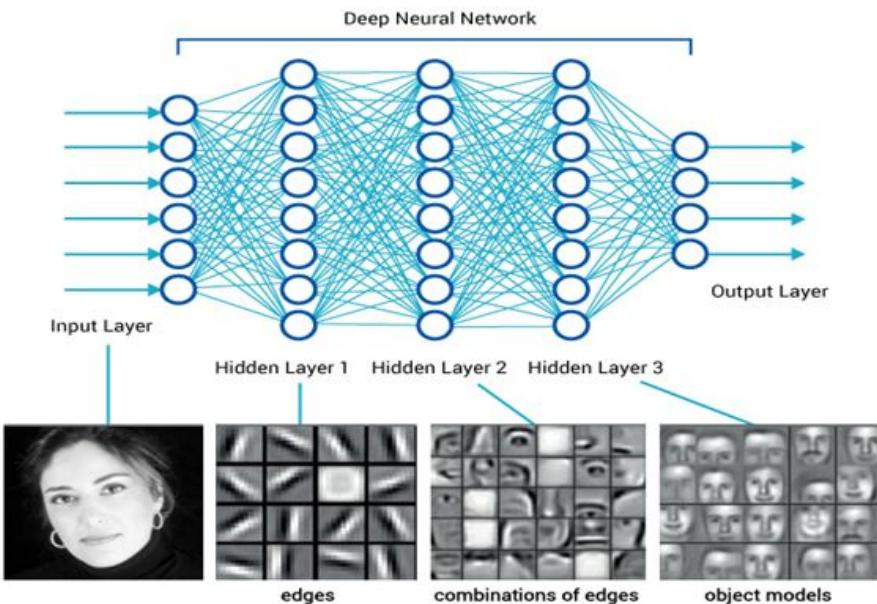
-1	1	0
-1	1	0
-1	1	0

0	0	0
1	1	1
-1	-1	-1

0	1	-1
0	1	-1
0	1	-1



Patterns in Conv Layers



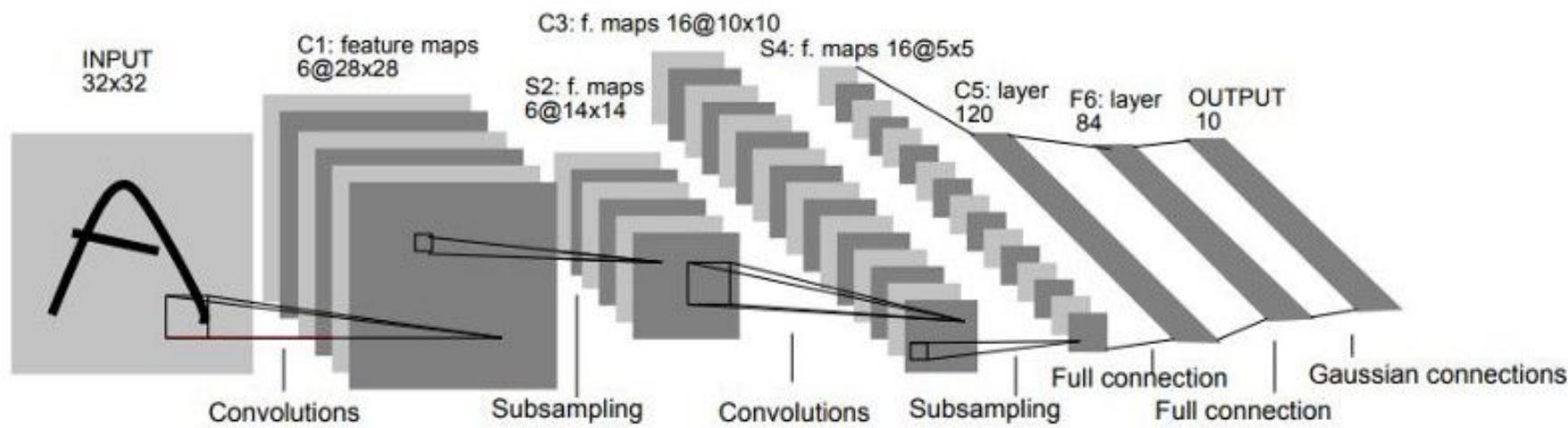
Advantages of ConvNets (vs. MLPs)

- Spatial Hierarchies and Feature Extraction
- Parameter Efficiency
- Translation Invariance
- Classical ConvNets
- Improved Generalization with Limited Data
- Adaptability to Transfer Learning

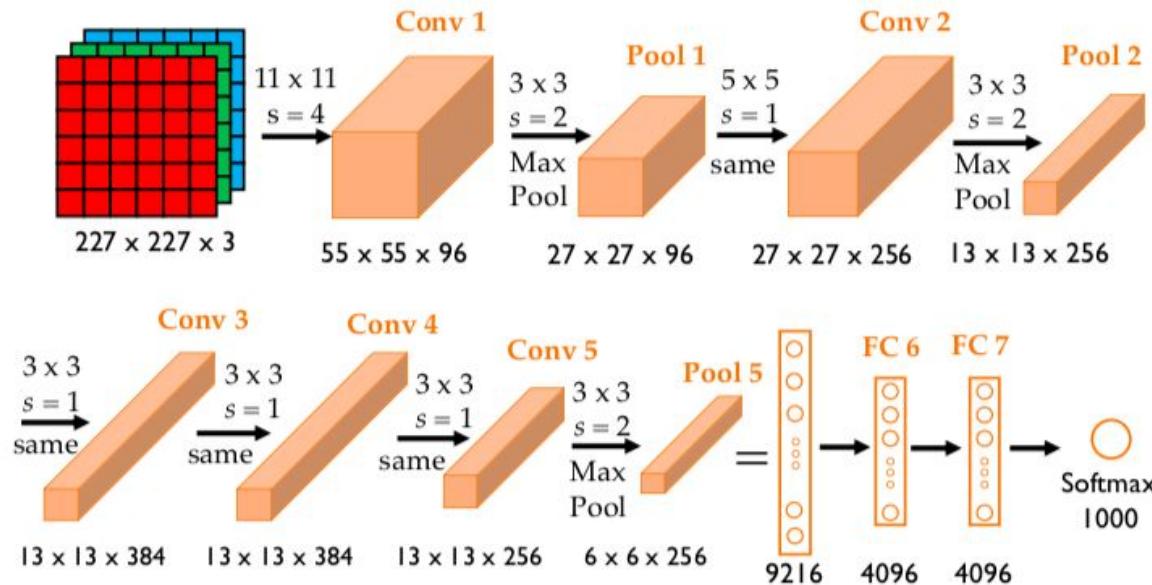
Online ConvNet Visualization

<https://poloclub.github.io/cnn-explainer/>

LeNet

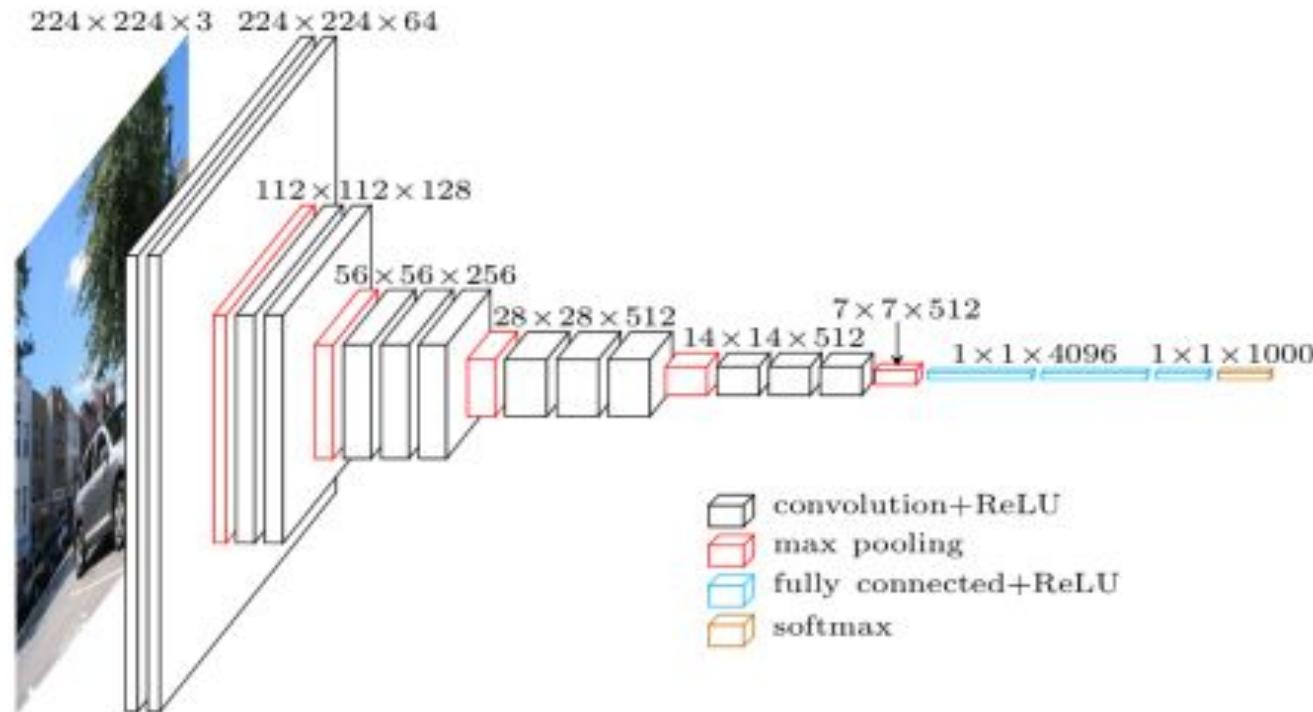


AlexNet



AlexNet

VGGNet

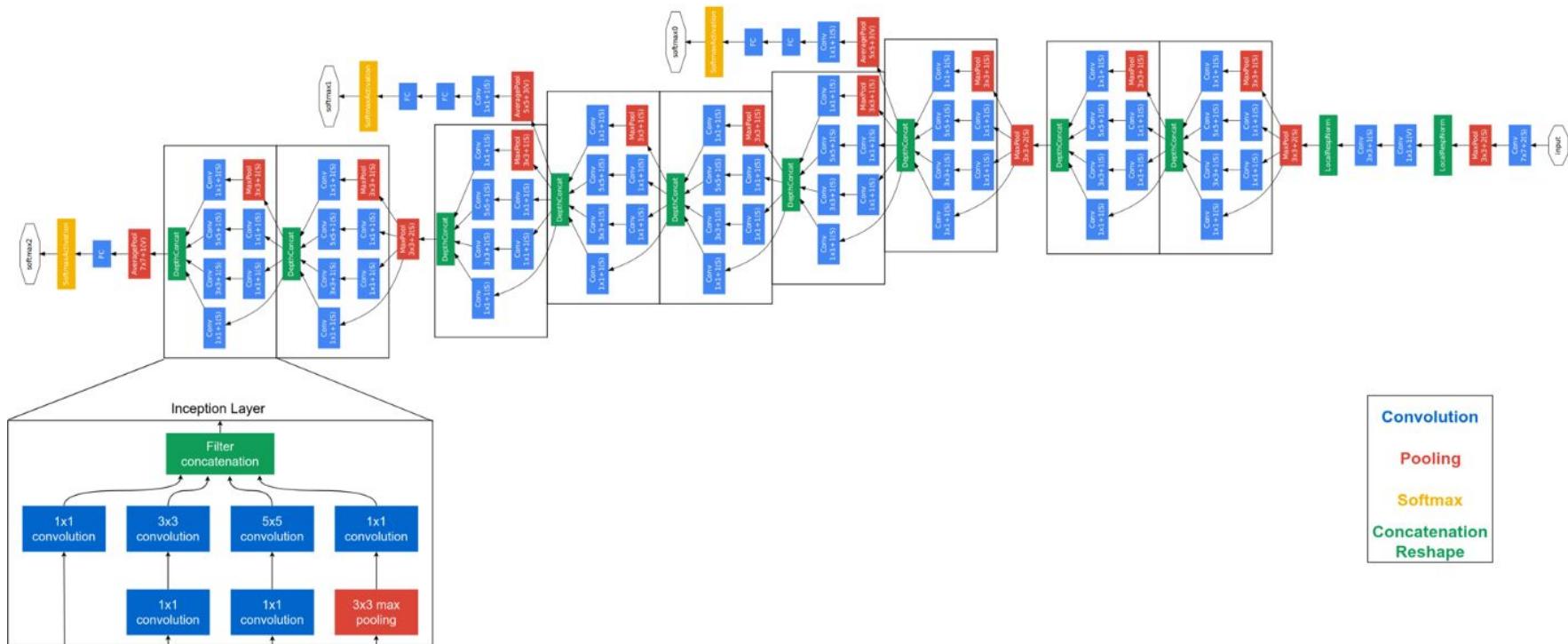


VGGNet+

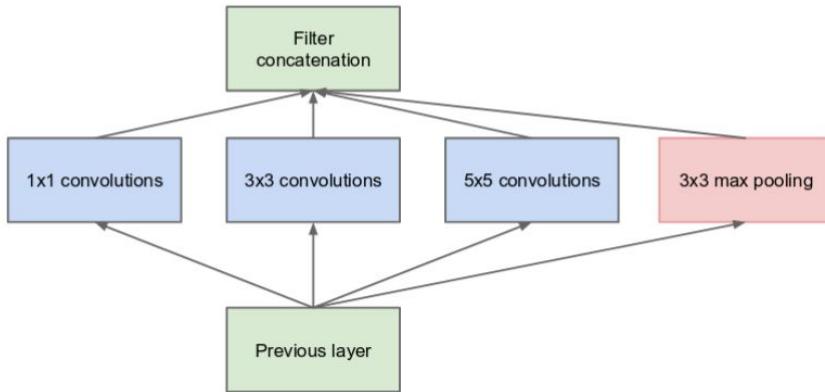
VGG16 - Structural Details

VGG16 - Structural Details													
#	Input Image			output			Layer	Stride	Kernel		in	out	Param
1	224	224	3	224	224	64	conv3-64	1	3	3	3	64	1792
2	224	224	64	224	224	64	conv3064	1	3	3	64	64	36928
	224	224	64	112	112	64	maxpool	2	2	2	64	64	0
3	112	112	64	112	112	128	conv3-128	1	3	3	64	128	73856
4	112	112	128	112	112	128	conv3-128	1	3	3	128	128	147584
	112	112	128	56	56	128	maxpool	2	2	2	128	128	65664
5	56	56	128	56	56	256	conv3-256	1	3	3	128	256	295168
6	56	56	256	56	56	256	conv3-256	1	3	3	256	256	590080
7	56	56	256	56	56	256	conv3-256	1	3	3	256	256	590080
	56	56	256	28	28	256	maxpool	2	2	2	256	256	0
8	28	28	256	28	28	512	conv3-512	1	3	3	256	512	1180160
9	28	28	512	28	28	512	conv3-512	1	3	3	512	512	2359808
10	28	28	512	28	28	512	conv3-512	1	3	3	512	512	2359808
	28	28	512	14	14	512	maxpool	2	2	2	512	512	0
11	14	14	512	14	14	512	conv3-512	1	3	3	512	512	2359808
12	14	14	512	14	14	512	conv3-512	1	3	3	512	512	2359808
13	14	14	512	14	14	512	conv3-512	1	3	3	512	512	2359808
	14	14	512	7	7	512	maxpool	2	2	2	512	512	0
14	1	1	25088	1	1	4096	fc		1	1	25088	4096	102764544
15	1	1	4096	1	1	4096	fc		1	1	4096	4096	16781312
16	1	1	4096	1	1	1000	fc		1	1	4096	1000	4097000
	Total								138,423,208				

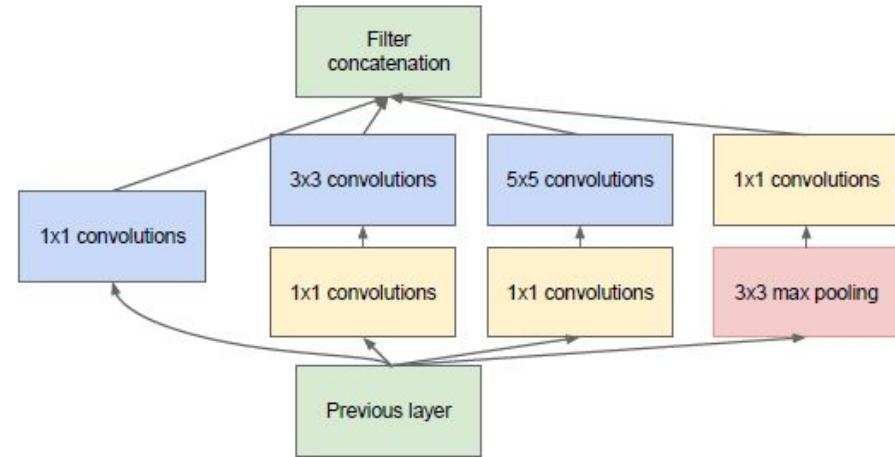
GoogLeNet (Inception)



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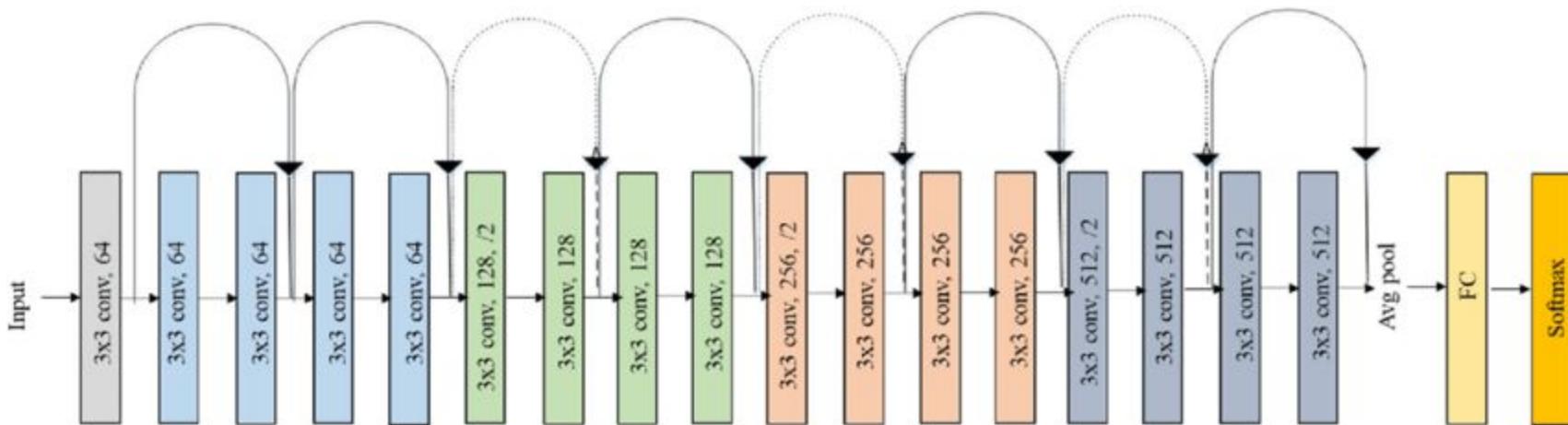
(a) Inception module, naïve version



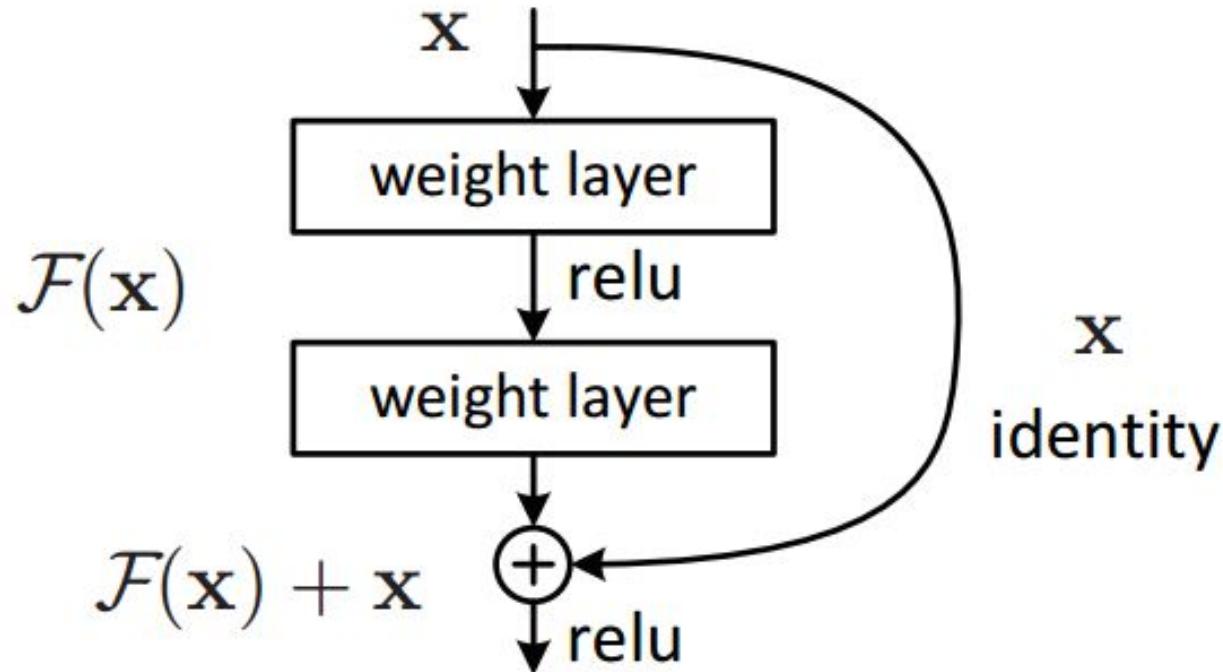
(b) Inception module with dimensionality reduction

GoogLeNet (Inception)

ResNet

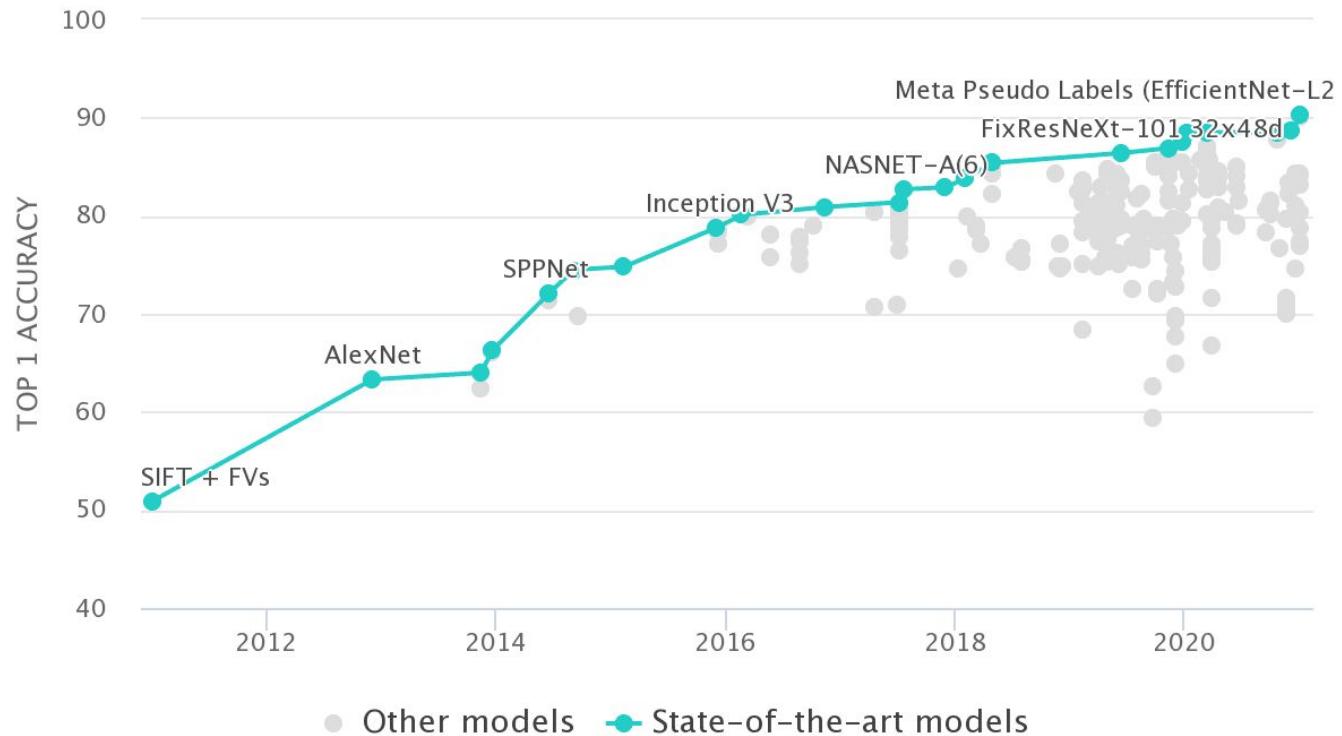


ResNet

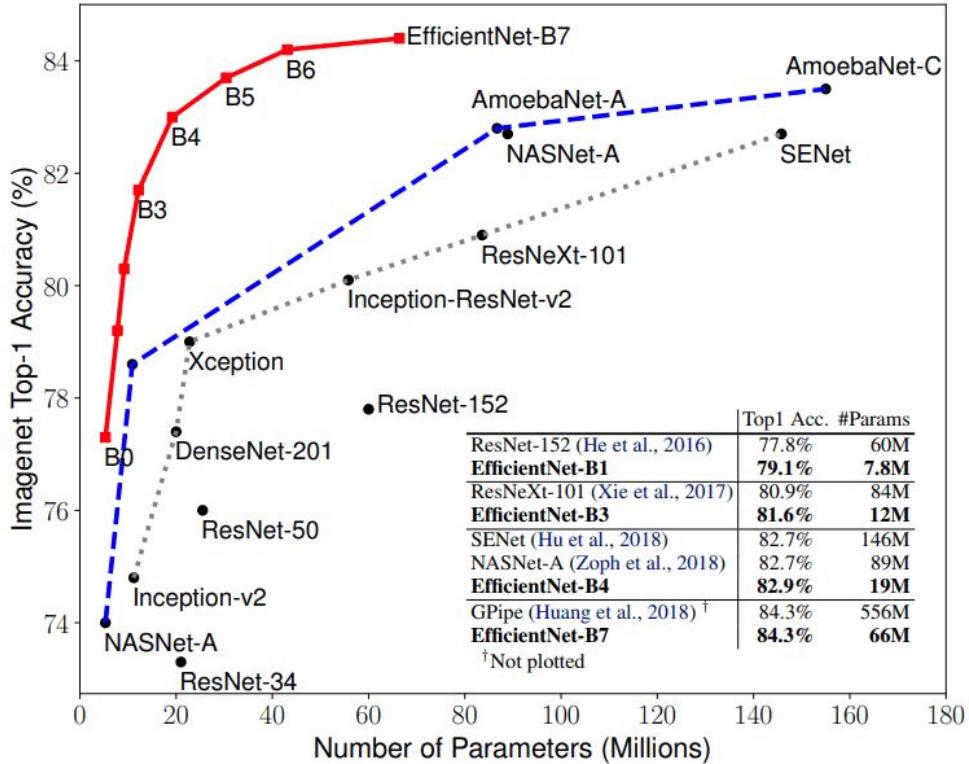
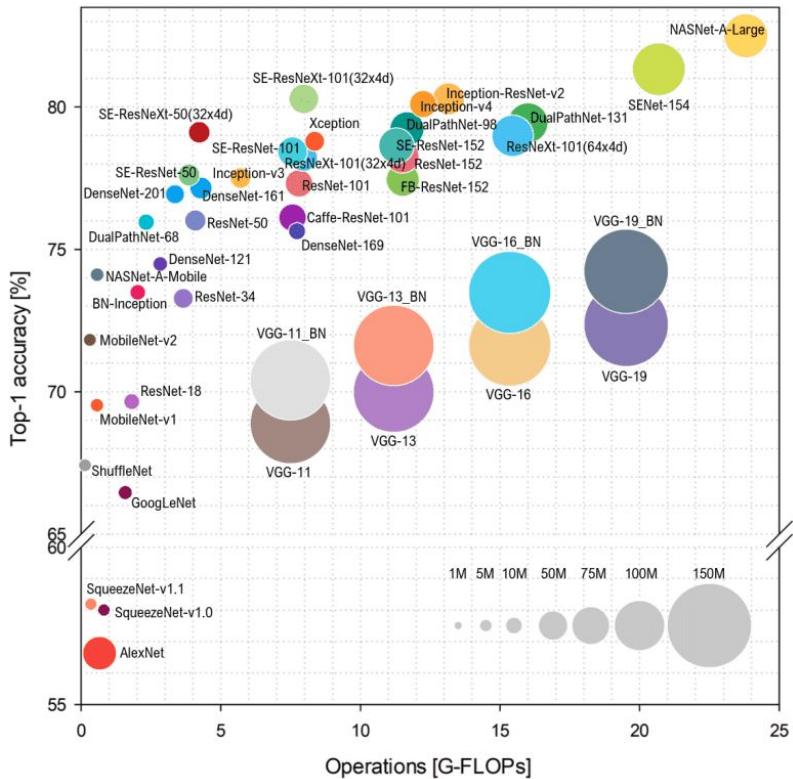


ResNet

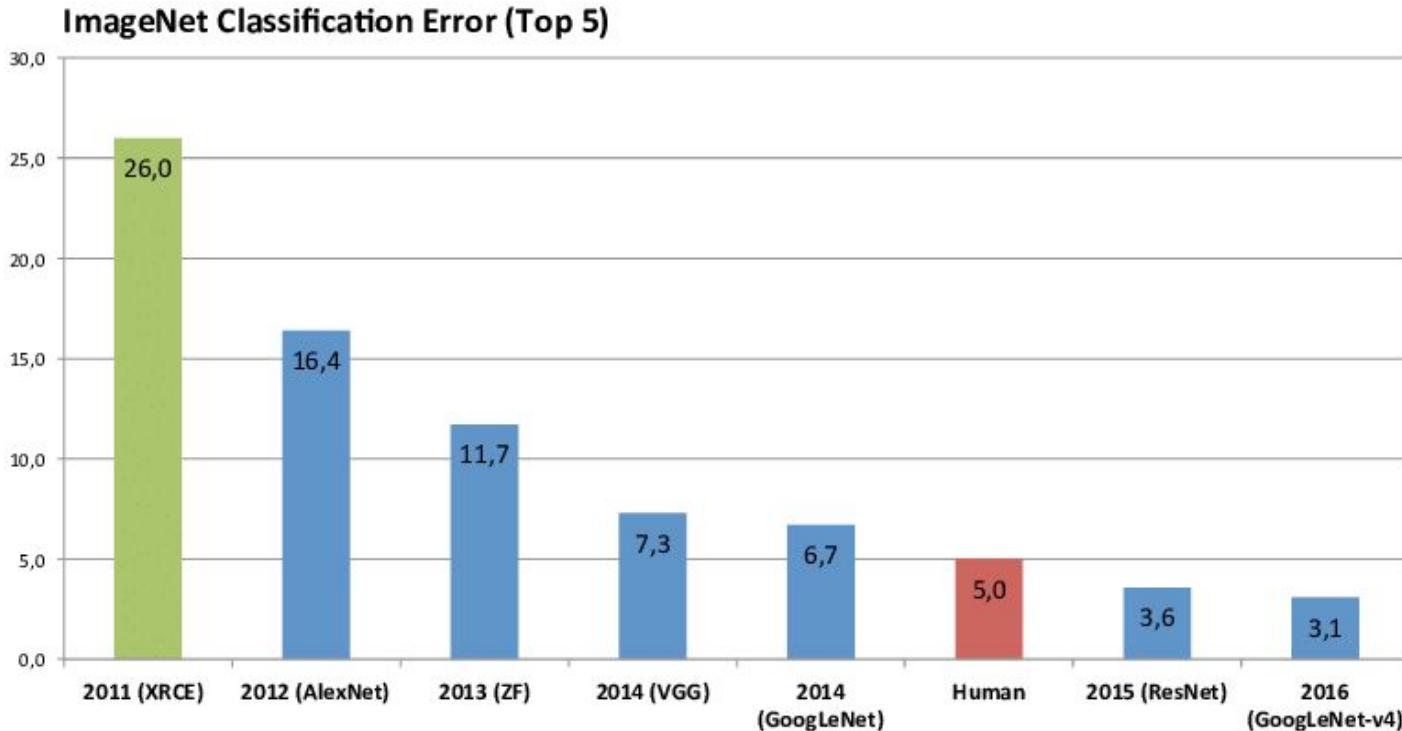
ConvNets Benchmarks



ConvNets Benchmarks



ConvNets Benchmarks



Russakovsky O, Deng J, Su H, Krause J, Satheesh S, Ma S, Huang Z, Karpathy A, Khosla A, Bernstein M, Berg AC. Imagenet large scale visual recognition challenge. International journal of computer vision. 2015 Dec;115(3):211-52.

ConvNets Implementation

- Models and pre-trained weights
- Transfer Learning Tutorial

