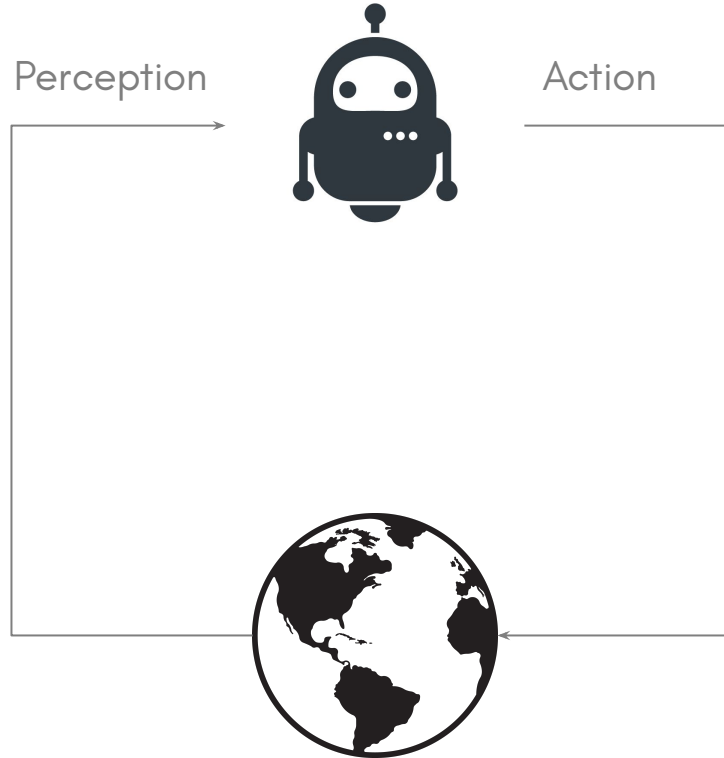


# ENGR 3421: Robotics I

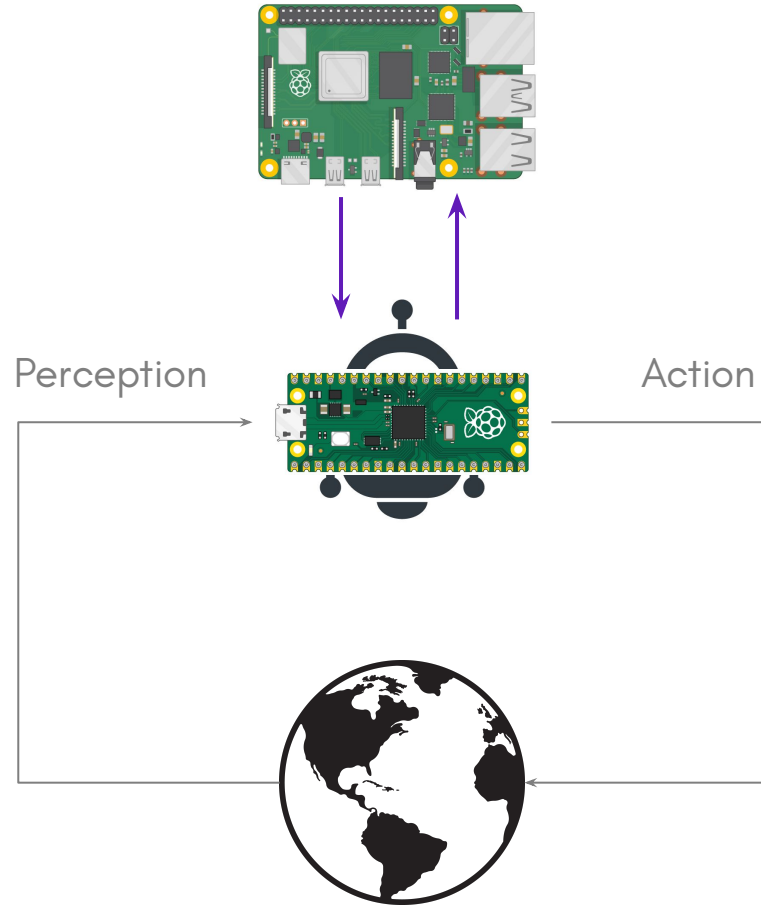
Communication

11/19/2024

# A Robot Needs to Talk and Listen



# A Robot Needs to Talk and Listen



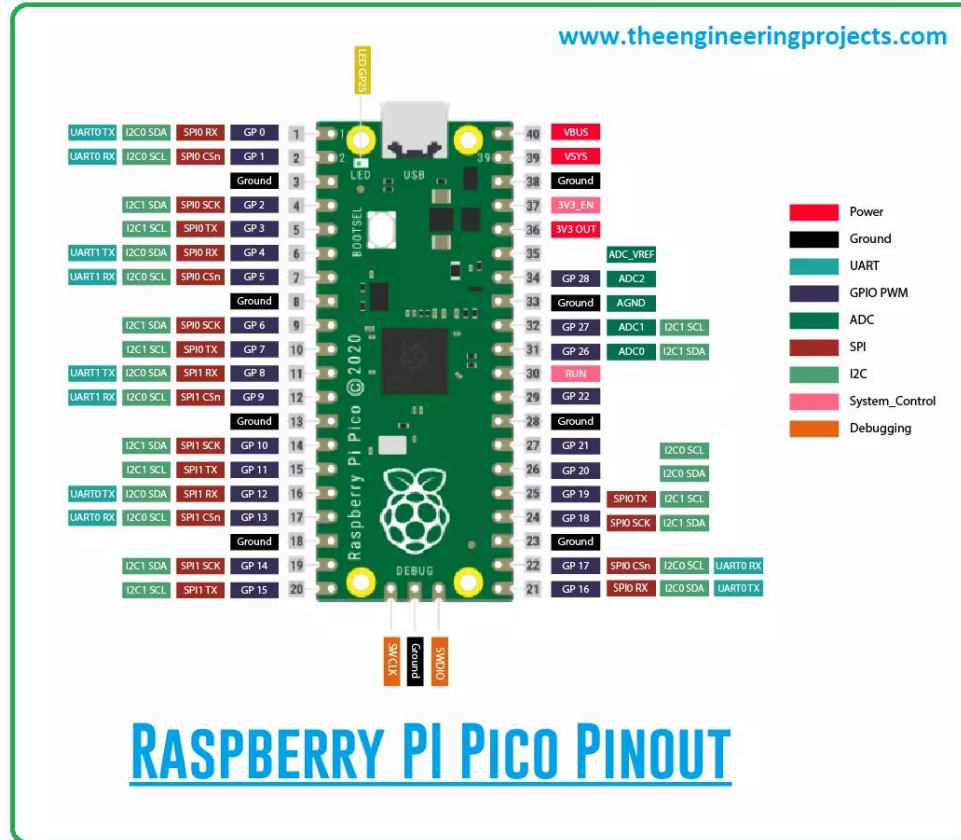
# Communication Protocols

Protocol	UART	I2C	SPI
Complexity	Simple	Easy to chain multiple devices	Complex as device increases
Speed	Slowest	Faster than UART	Fastest
Number of devices	Up to 2 devices	Up to 127, but gets complex	Many, but gets complex
Number of wires	1	2	4
Duplex	Full Duplex	Half Duplex	Full Duplex
No. of masters and slaves	Single to Single	Multiple slaves and masters	1 master, multiple slaves

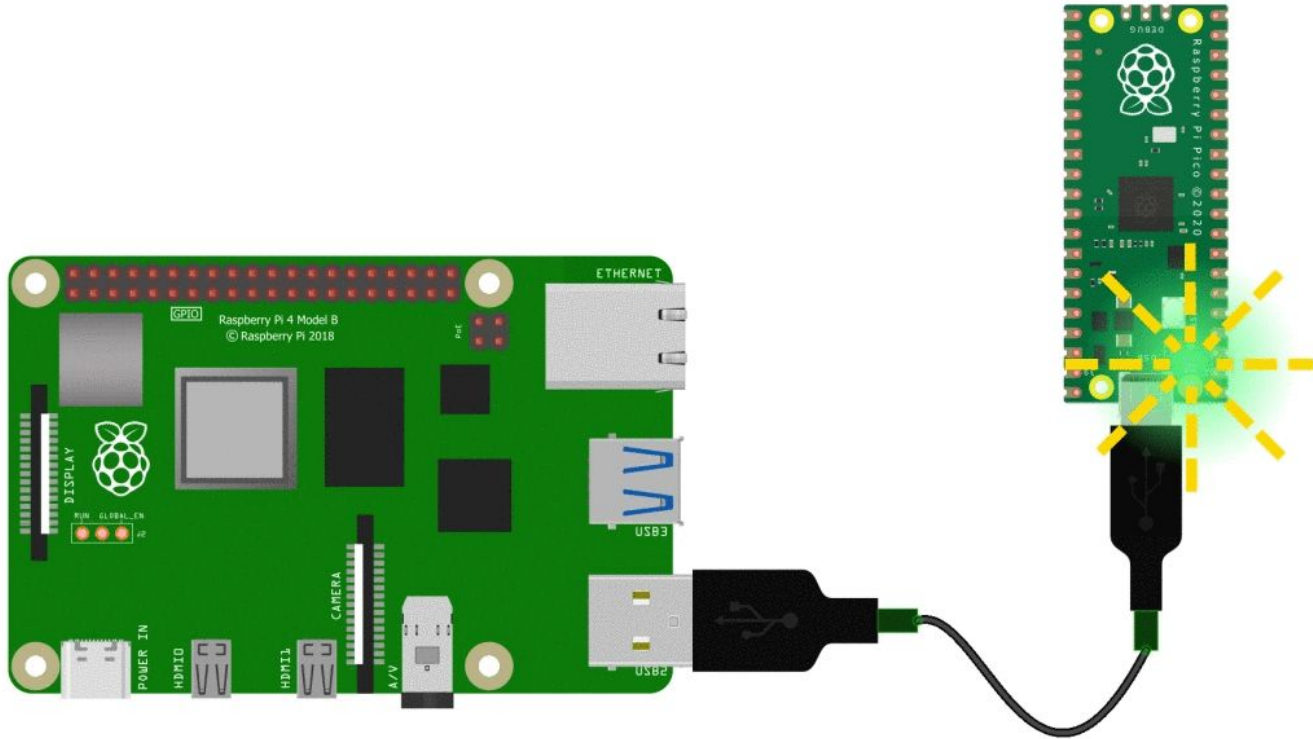
# Communication Protocols

	i2C	SPI	UART
<b>Diagram</b>			
<b>Complexity</b>	Simplex	Duplex	1 to 1
<b>Synchronization</b>	Synchronous	Synchronous	Asynchronous
<b>Wires</b>	2 wire	4+ wire	2 wire
<b>Speed</b>	1 Mbps	25 Mbps	20Kbps
<b>Acknowledgment</b>	NO Acknowledge	NO Acknowledge	Acknowledge pins
<b>Power</b>	Medium Power	Low Power	Medium Power
<b>Distance</b>	1m Distance	20m Distance	15m Distance

# Communication Interfaces on Pico

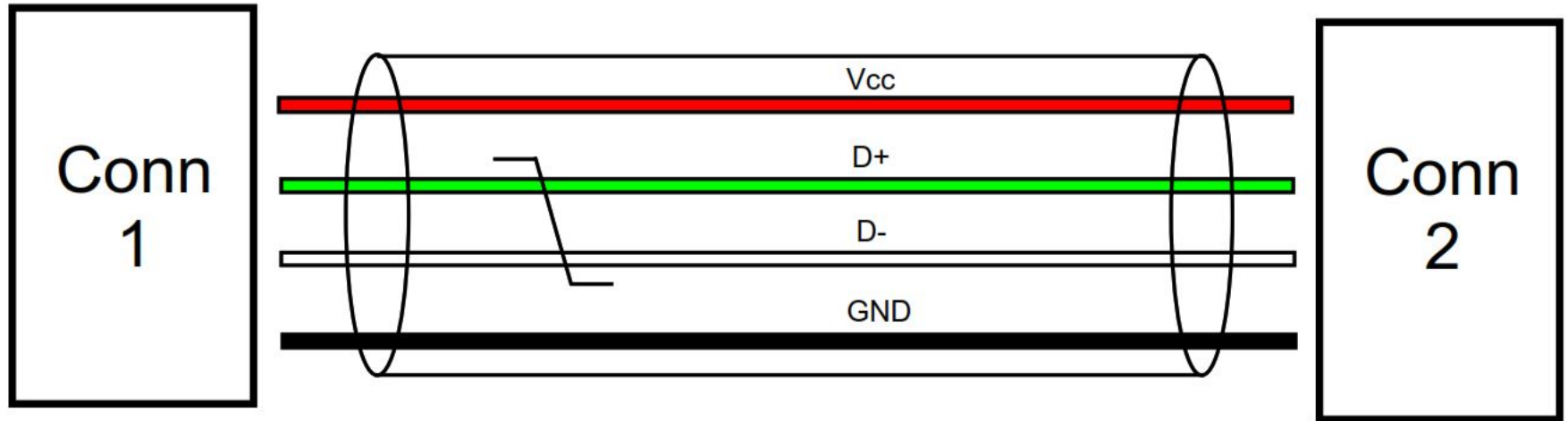


# USB Serial Bus



# USB Serial Bus

SINGLE USB 2.0 CABLE





# Examples

<https://github.com/linzhangUCA/3421example-communicate>